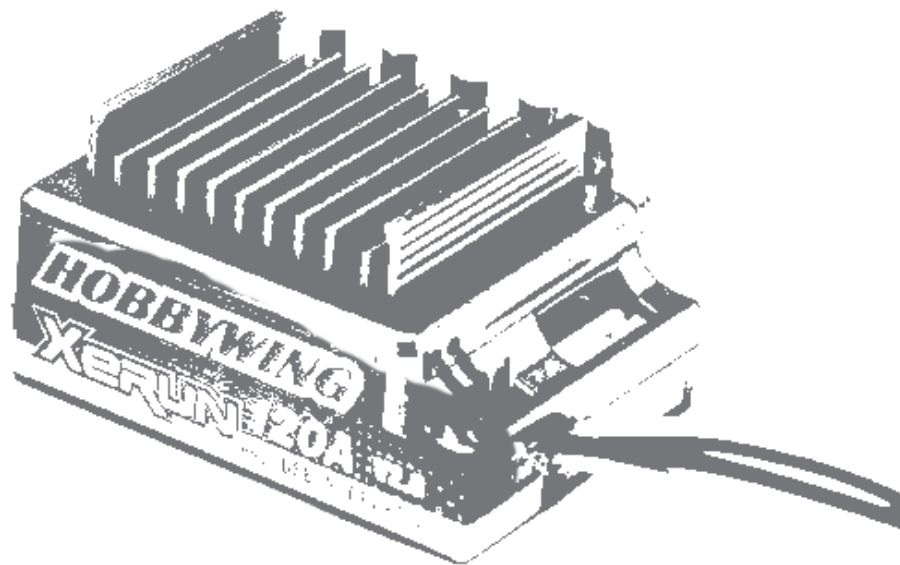




User Manual

Brushless Speed Controller

XERUN 60A/120A



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DECLARATION

Thanks for purchasing the Electronic Speed Controller (ESC). High power system for RC model can be very dangerous, so please read this manual carefully. In that we have no control over the correct use, installation, application, or maintenance of our products, no liability shall be assumed nor accepted for any damages, losses or costs resulting from the use of the product. Any claims arising from the operating, failure of malfunctioning etc. will be denied. We assume no liability for personal injury, consequential damages resulting from our product or our workmanship. As far as is legally permitted, the obligation to compensation is limited to the invoice amount of the affected product.

FEATURES

- ▶ Compatible with all sensorless brushless motors and most of sensored brushless motors such as LRP, SpeedPassion, Novak, etc.
- ▶ Seamlessly change to sensorless working mode when the sensor cable is broken.
- ▶ Excellent start-up, acceleration and linearity features.
- ▶ Built-in BEC has a powerful output to supply all the electronic equipments.
- ▶ Firmware can be updated through an USB adapter on the advanced LCD Program Box (Optional equipment).
- ▶ User programmable. Easily programmed with the "SET" button on the ESC and also compatible with the 3 digital LEDs Program Card and the advanced professional LCD Program Box.
 - 3 running modes (Forward mode, Forward/Reverse mode, Rock Crawler mode)
 - 4 steps of maximum reverse force adjustment.
 - Proportional ABS brake function with 4 steps of maximum brake force adjustment, 8 steps of drag-brake force adjustment and 4 steps of initial brake force adjustment.
 - 9 start modes (Also called "Punch") from "very soft (Level 1)" to "very aggressive (Level 9)".
 - 8 steps of timing adjustment to suitable for all brushless motors.
 - Multiple protection features: Low voltage cut-off protection / Over-heat protection / Throttle signal loss protection / Motor blocked protection.

SPECIFICATIONS

MODEL	XERUN-120A-V2	XERUN-60A-V2	
Cont./ Burst Current	120A / 760A	60A/360A	
Resistance	0.0003 ohm	0.0006 ohm	
Suitable Car	1/10, 1/12 on-road & off-road, 1/8, 1/10 scale rock crawler		
Suitable Motor	Sensored and sensorless Brushless Motors		
	5-6 NIMH or 2 Lipo	≥3.5T(on-road), ≥5.5T(off-road)	≥5.5T(on-road), ≥8.5T(off-road)
	8-9 NIMH or 3 Lipo	≥5.5T (on-road), ≥8.5T(off-road)	≥10.5T(on-road), ≥17.5T(off-road)
Battery	4-9 cells NIMH or 2-3 cells Li-Po		
BEC Output	5.75V@3A Built-in BEC		
Dimension	43mm(L) * 36mm(W) * 33mm(H)		
Weight	105g	80g	
Fan Working Voltage *	5V@0.16A, maximum 8V. (The fan gets the power supply directly from the battery)		

* Please choose 12V cooling fan when using 3 cells Lipo.

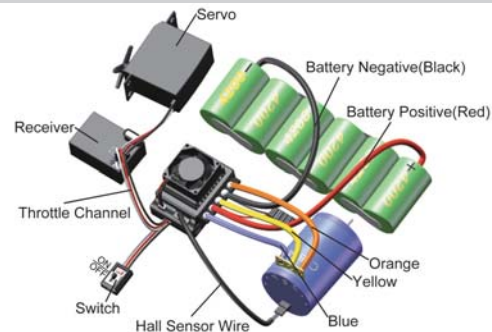
BEGIN TO USE NEW ESC

1 Connect the ESC, motor, receiver, battery and servo correctly.

A) Sensored brushless motor wiring

When using brushless motor with Hall Sensor, it is necessary to connect the sensor cable to the "SENSOR" socket on the ESC, and ESC can automatically identify the motor type (sensored or sensorless) by detecting the signal coming from the SENSOR socket.

WARNING! For sensored brushless motor, the #A, #B, #C wires of the ESC MUST be connected with the motor wire #A, #B, #C respectively. Do not change the wires sequence optionally!



B) Sensorless brushless motor wiring

When using brushless motor without Hall Sensor, the #A, #B, #C wires of the ESC can be connected with the motor wires freely (without any sequence). If the motor runs in the opposite direction, please swap any two wire connections.

⚠ Note: For SENSORLESS motor, you can also set the throttle channel of your transmitter to the "REVERSE" direction, and then the motor will run oppositely. And please calibrate the throttle range again after changing the direction of throttle channel. Please keep in mind that this method is ONLY available for SENSORLESS motor.

2 Throttle Range Setting (Throttle Range Calibration)

In order to make the ESC fit the throttle range, you must calibrate it when you begin to use a new ESC, or a new transmitter, or change the settings such as the neutral position of the throttle stick, ATV or EPA parameters, etc. Otherwise the ESC cannot work properly.

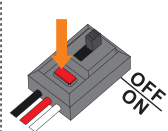
There are 3 points need to be set, they are the "Top point of forward", the "Top point of backward" and the "Neutral point".

The following pictures show how to set the throttle range with a Futaba™ transmitter.

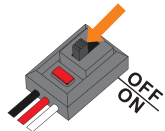
A) Switch off the ESC, turn on the transmitter, set the direction of throttle channel to "REV", set the throttle trim to "0", set the "EPA/ATV" value of throttle channel to "100%", and disable the ABS function of your transmitter.

B) Use a pen or screw driver to hold the "SET" key and then switch on the ESC, and release the "SET" key as soon as possible when the red LED begins to flash.

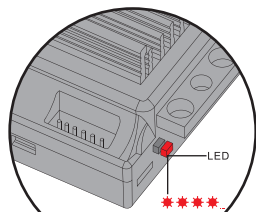
Note: If you don't release the "SET" key as soon as the red LED begins to flash, the ESC will enter the program mode, in such a case, please switch off the ESC and re-calibrate the throttle range again from step A to step D.



Hold the red button



Turn on ESC



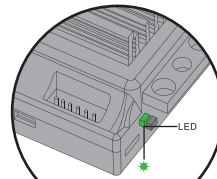
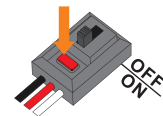
Release the red button as soon as the red LED begins to flash

C) Set the 3 points according to the steps shown as the pictures on the right side.

- ▶ The neutral point
- ▶ The top point of forward direction
- ▶ The top point of backward direction

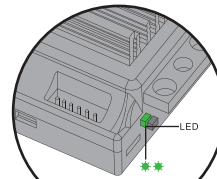
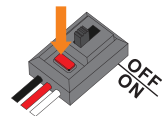
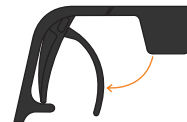
D) When the process of calibration is finished, the motor can be started after 3 seconds.

① Neutral point



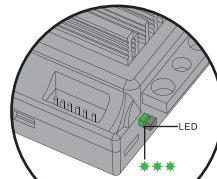
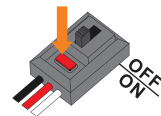
The green LED flashes 1 time

② Top point of forward direction



The green LED flashes 2 times

③ Top point of backward direction



The green LED flashes 3 times

PROGRAM THE ESC

1 Programmable Items List (The blue color texts in the form are the default settings)

Programmable Items	Options								
	1	2	3	4	5	6	7	8	9
Basic Items									
1. Running Mode	Forward with Brake	Forward/Reverse with Brake	Foward/Reverse (For Rock Crawler)						
2. Drag Brake Force	0%	5%	10%	20%	40%	60%	80%	100%	
3. Low Voltage Cut-Off Threshold	No-Protection	2.6V /Cell	2.8V /Cell	3.0V /Cell	3.2V /Cell	3.4V /Cell			
4. Start Mode(Punch)	Level1	Level2	Level3	Level4	Level5	Level6	Level7	Level8	Level9
Advanced Items									
5. Max Brake Force	25%	50%	75%	100%					
6. Max Reverse Force	25%	50%	75%	100%					
7. Initial Brake Force	= Drag Brake Force	0%	20%	40%					
8. Neutral Range	6% (Narrow)	9% (Normal)	12% (Wide)						
9. Timing	0.00 °	3.75 °	7.50 °	11.25 °	15.00 °	18.75 °	22.50 °	26.25 °	
10. Over-heat Protection	Enable	Disable							

2 Explanation For Each Programmable Item

2.1. Running Mode: With "Forward with Brake" mode, the car can go forward and brake, but cannot go backward, this mode is suitable for competition; "Forward/Reverse with Brake" mode provides backward function, which is suitable for daily training.

Note: "Forward/Reverse with Brake" mode uses "Double-click" method to make the car go backward. When you move the throttle stick from forward zone to backward zone for the first time (The 1st "click"), the ESC begins to brake the motor, the motor speeds down but it is still running, not completely stopped, so the backward action is NOT happened immediately. When the throttle stick is moved to the backward zone again (The 2nd "click"), if the motor speed is slowed down to zero (i.e. stopped), the backward action will happen. The "Double-Click" method can prevent mistaken reversing action when the brake function is frequently used in steering. In the process of brake or reverse, if the throttle stick is moved to forward zone, the motor will run forward at once.

"Forward/Reverse" mode uses "Single-click" method to make the car go backward. When you move the throttle stick from forward zone to backward zone, the car will go backward immediately. This mode is usually used for the Rock Crawler.

2.2. Drag Brake Force: Set the amount of drag brake applied at neutral throttle to simulate the slight braking effect of a neutral brushed motor while coasting.

2.3. Low Voltage Cut-Off: The function prevents the lithium battery pack from over discharging. The ESC detects the battery's voltage at any time, if the voltage is lower than the threshold for 2 seconds, the output power will be reduced 70%, after 10 seconds the output power will be completely shut off and the red LED flashes in such a way: "***, ***, ***". Please stop your car at the track side as soon as possible to avoid obstructing other racing cars. For stock motors, 3.4V/Cell cutoff threshold is suggested.

Please note that the cutoff threshold is calculated for each LITHIUM (Lipo) battery cell. For NiMH battery packs, if the voltage of the whole NiMH battery pack is higher than 9.0V, it will be considered as a 3 cells lithium battery pack; If it is lower than 9.0V, it will be considered as a 2 cells lithium battery pack. For example, a NiMH battery pack is 8.0V, and the threshold is set to 2.6V/Cell, so it will be considered as a 2 cells lithium battery pack, and the low-voltage cut-off threshold for this NiMH battery pack is 2.6*2=5.2V.

There are 6 preset options for this programmable item. You can customize the cutoff threshold by using an advanced LCD Program Box (Optional equipment) to trim it with a step of 0.1V, so it will be more suitable for all kinds of batteries (NiMH, NiCd, Li-ion, Lipo, LFP, etc).

⚠ Please always keep in mind that the customized value is not for each Lipo battery cell, it is for the WHOLE battery pack.

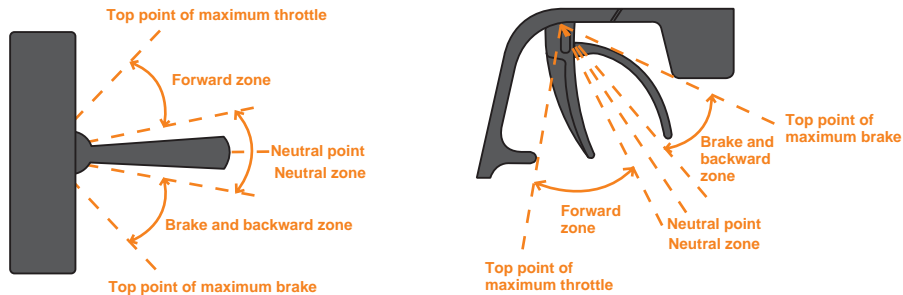
2.4. Start Mode (Also called "Punch"): Select from "Level1" to "Level9" as your like, Level1 has a very soft start effect, while level9 has a very aggressive start effect. From Level1 to Level9, the start force is increasing. Please note that if you choose "Level7" to "Level9" mode, you must use good quality battery pack with powerful discharge ability, otherwise these modes cannot get the burst start effect as you want. If the motor cannot run smoothly (the motor is trembling), it may caused by the weak discharge ability of the battery pack, please choose a better battery or increase the gear rate (Use a smaller pinion).

2.5. Maximum Brake Force: The ESC provides proportional brake function. The brake force is related to the position of the throttle stick. Maximum brake force refers to the force when the throttle stick is located at the top point of the backward zone. A very large brake force can shorten the brake time, but it may damage the gears.

2.6. Maximum Reverse Force: Sets how much power will be applied in the reverse direction. Different value makes different reverse speed.

2.7. Initial Brake Force: It is also called "minimum brake force", and it refers to the force when the throttle stick is located at the initial position of the backward zone. The default value is equal to the drag brake force, so the brake effect can be very smoothly.

2.8. Throttle Neutral Range: Please refer to the following picture to adjust the neutral range as your like.



2.9. Timing: The "timing" item is usable for both sensed and sensorless brushless motors. Please select the most suitable timing value according to the motor you are just using. Generally, higher timing value brings out higher power output, but the whole efficiency of the system will be slightly lower down.

⚠ Note: For ESC firmware later than 091218A, if the ESC works with a MODIFY motor, please don't choose timing values larger than 18.75°, otherwise the motor maybe over heat and damaged.

2.10. Over-Heat Protection: If the function is activated, the output power will be cut-off when the temperature of the ESC or the internal temperature of the sensed brushless motor is high than a factory-preset value for 5 seconds. When the protection happens, the Green LED will flash.

▶ When the ESC is over-heat: The Green LED flashes as "★, ★, ★" (Single flash).

▶ When the motor is over-heat: The Green LED flashes as "★★, ★★, ★★" (Double flash).

⚠ Note: The motor over-heat protection function is only available for the sensed brushless motor made by HOBBYWING. For motors made by other manufacturers, this function maybe not available or the protection point doesn't match the design of the ESC, please disable the over-heat protection function in such a case.

3 Program Methods

A) Program the ESC with LED program card (Optional equipment)
Please refer to the user manual of LED program card.

B) Program the ESC with advanced LCD program box (Optional equipment)
Please refer to the user manual of LCD program box.

C) Program the ESC with the SET button on the ESC
Please refer to the flow chart at page 10.



Note:

▶ In the program process, when the LED is flashing, the motor will emit "Beep" tone at the same time.

▶ If the number "N" is bigger than the "5", we use a long time flash and long "Beep—" tone to represent "5", so it is easy to identify the items with bigger series number.

For example, if the LED flashes as the following:

"A long time flash + 1 short time flash" (Motor sounds "Beep—Beep") = the No. 6 item

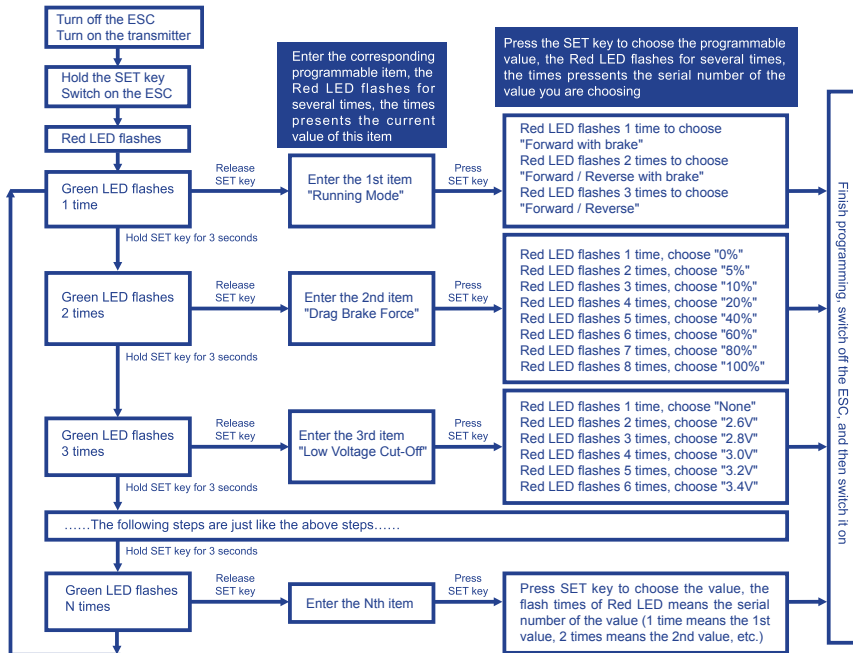
"A long time flash + 2 short time flashes" (Motor sounds "Beep—BeepBeep") = the No. 7 item

"A long time flash + 3 short time flashes" (Motor sounds "Beep—BeepBeepBeep") = the No. 8 item

And so on.

4 Reset All Items To Default Values

At any time when the throttle is located in neutral zone (except in the throttle calibration process or program mode), hold the "SET" key more than 3 seconds, the red LED and green LED will flash at the same time, which means each programmable item has be reset to its default value.



ALERT TONES AND LED STATUS

- 1** Input voltage abnormal alert tone: The ESC begins to check the input voltage when power on, if the voltage is out of the normal range, such an alert tone will be heard: "beep-beep-, beep-beep-, beep-beep-" (There is 1 second interval between every group of "beep-beep-" tone).
- 2** Throttle signal abnormal alert tone: When the ESC can't detect the normal throttle signal, such an alert tone will be heard: "beep-, beep-, beep-" (There is 2 seconds interval between every "beep-" tone).
- 3** The LED Status In Normal Running
 - ▶ Normally, if the throttle stick is in the neutral range, neither the red LED nor the green LED lights.
 - ▶ The red LED lights when the car is running forward or backward and it will flash quickly when the car is braking.
 - ▶ The green LED lights when the throttle stick is moved to the top point of the forward zone.

BRUSHLESS SYSTEM CONFIGURATION SUGGESTION

Motor	KV/ Power	Gear Rate		Suitable ESC	Application
		1/10 On Road	1/10 Off Road		
3.5T	9100KV/600W	9.6-11.0		120A	1/10, 1/12 On-road competitive racing (Modified group)
4.5T	7300KV/500W	8.4-10.0		120A	
5.5T	6000KV/400W	8.0-9.4	10.0-12.0	120A	1/10 On-Road sportful racing
6.5T	5200KV/350W	7.4-8.4	9.0-11.0	120A	1/10 Off-road competitive racing (Modified group)
8.5T	4000KV/300W	6.0-7.0	8.0-9.6	120A/60A	1/10, 1/12 On-Road sportful racing 1/10, 1/12 Off-Road sportful racing
10.5T	3300KV/250W	5.0-6.0	7.5-8.5	120A/60A	
13.5T	2700KV/200W	4.5-5.5	7.0-8.0	120A/60A	
17.5T	1900KV/150W	4.5-5.5	6.0-8.0	120A/60A	

Note:

The "Power of motor" means the maximum output power under 7.2V.

The "Gear rate" is just the recommended value for 1/10 scale car/truck under 6 cells NiMH battery input.

TROUBLE SHOOTING

Trouble	Possible Reason	Solution
After power on, motor doesn't work, no sound is emitted	The connections of battery pack are not correct The switch is damaged	Check the power connections, replace the connectors or switch
After power on, motor can't work, emits "beep-beep-, beep-beep-" alert tone. (Every group "beep-beep-" has time interval of 1 sec)	Input voltage is abnormal, too high or too low.	Check the voltage of the battery pack
After power on, the red LED lights, but motor cannot run	Throttle signal is abnormal	Check the transmitter and the receiver, and check the signal wire connection of your ESC
The motor runs in the opposite direction	1) The wire connections between the ESC and the motor need to be changed 2) The chassis is not suitable for this ESC	1) Swap any two wire connections between the ESC and the motor. (Note: This method is ONLY available for SENSORLESS motor) 2) Please don't use the ESC for this special chassis.
The motor stops running while in working state	The ESC has entered the "Low voltage protection mode" or the "Over-heat protection mode"	The red LED flashes means Low voltage protection, please replace the battery pack The green LED flashes means Over-heat protection, please wait for some minutes to cool the ESC
When accelerating quickly, the motor stops or trembles	1) The battery hasn't a good discharge performance 2) The gear rate is not suitable, so the motor load is too heavy	1) Use a better battery 2) Use lower KV motor or change the gear rate or set the "Start Mode" more softly
When the throttle stick is in the neutral range, the red LED and the green LED flashes synchronously	The motor is a sensored motor, but the ESC detects abnormal signal from the sensor, so it changes to sensorless mode automatically	1) Check the connection of Hall sensor cable to make it firmly connecting the motor with the ESC 2) The Hall sensors in the motor are damaged, please change the motor
The motor trembles but cannot start smoothly	1) The connections are not A-A, B-B and C-C 2) The ESC is damaged	1) Check the connections 2) Contact the dealer for after-sales service

WARRANTY INFORMATION

The XERUN series ESC is warranted for 240 days from the date of production to be free of material and workmanship defects. This warranty does not cover abuse, neglect, or damage due to incorrect wiring, over voltage or over loading.

An itemed Warranty Card must accompany any product returned for warranty work. The serial number on the warranty card must be identical with the serial number of the ESC.

Please browse <http://www.hobbywing.com/english/kf.asp> for more detail warranty information.